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~~Doing Motion Planning~~
~~programmatically ROS BASICS~~

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*IN 5 DAYS #2 - Learn ROS
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Programming Turtlebot*

ROS NAVIGATION IN 5 DAYS #1
- Course Overview \u0026

~~Basics Concepts ROS BASICS IN
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~~Robotic Challenge Solve |
Basic ROS Learning Week day
5 | Turtlebot2 Basic ROS
Learning Week - Day 1: Linux
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138 - How to set a sequence
of goals in MoveIt for a
manipulator? **Basic ROS**~~

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Learning Week – Day 5:

Program a robot with ROS ROS

NAVIGATION IN 5 DAYS #4 –

Path Planning – Part 1

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Indoor Mapping and

Navigation Robot Build with

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ROS and Nvidia Jetson Nano

ROS / TurtleBot SLAM

[Tutorial] You can learn

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KALARO KO POSER KO ! (ROS
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Arm controlled with Arduino
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and Trajectory Execution of

a robot manipulator using

ROS Moveit and Arduino. ROS

kinetic tutorial #05 ROS

topic, nodes, messages P1

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Custom MESSAGES in ROS |
Tutorial #5 | ROS and
Raspberry Pi **Robot Modeling**
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ROS BASICS IN 5 DAYS #7 -

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ROS Services | Part 2 Basic

ROS Learning Week - Day 3:

ROS Basic concepts

(packages, nodes, launches...)

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Path Planning - Part 2 5 ROS

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Learning Methods: which one
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Future of Robotic

Manipulation with ROS and

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ROS Manipulation in 5 days:

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ROS Manipulation is the term used to refer to any robot that manipulates something in its environment. The main

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goal of this Course is to teach you the basic tools you need to know in order to be able to understand how ROS Manipulation works, and teach you how to implement it for any manipulator robot.

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About The Book. ROS in 5
days is the book associated
with a course giving you the
basic tools and knowledge to
be able to understand and
create any basic ROS-related

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project. You will be able to move robots, read their sensor data, do parallel tasks, see visual representations of complex data... and much more. This course is divided into two main parts.

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